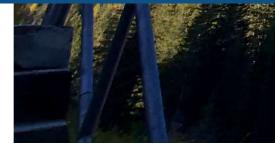
Institute of Geodesy and Photogrammetry





# Automated Inspection within Galleries of Large Dams

Helena LAASCH, Nathalie RYTER, Isabelle STEFFEN, Alexander RESKE, Ephraim FRIEDLI, Valens FRANGEZ, Switzerland



## Structural Health Monitoring and Inspection



1. DSLM camera *Lumix DMC-FZ2000* Pixel size at 1 m : 0.3 mm/px

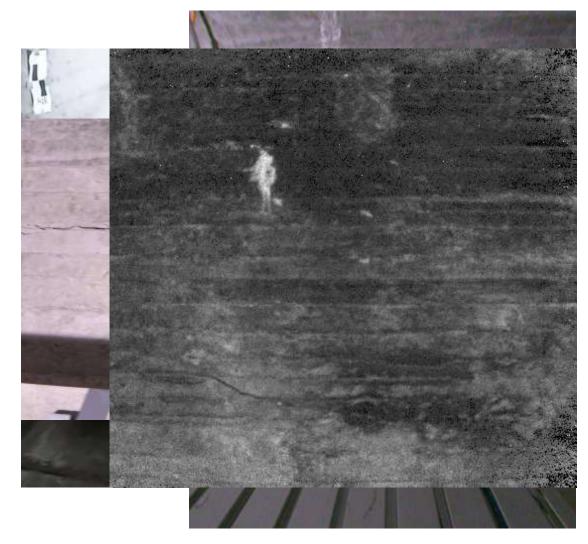


2. Mapping system *Leica BLK2Go* Pixel size at 1 m : 1.6 mm/px



3. Depth camera Helios Time of Flight 3D Camera Pixel size at 1 m : 1.7 mm/px







#### DSLM



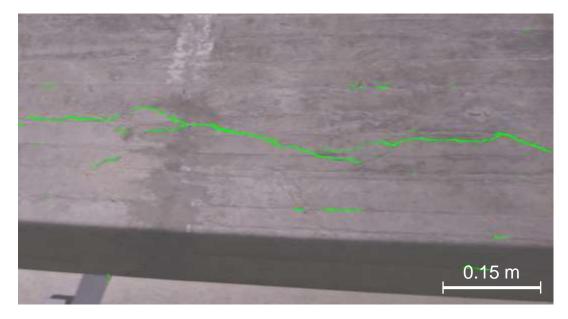
#### BLK2GO



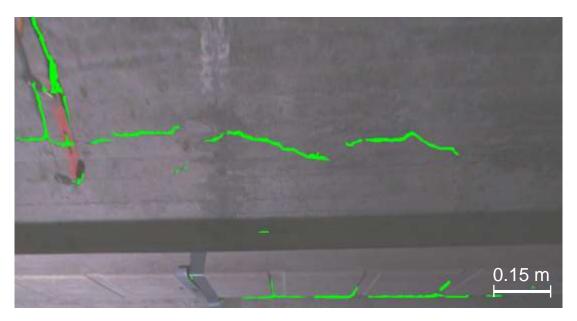
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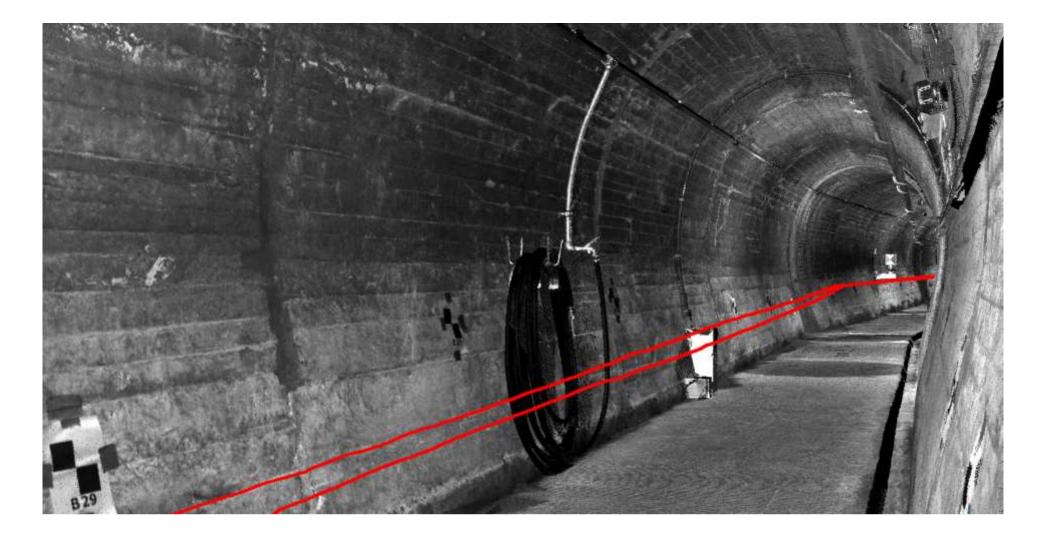
#### DSLM



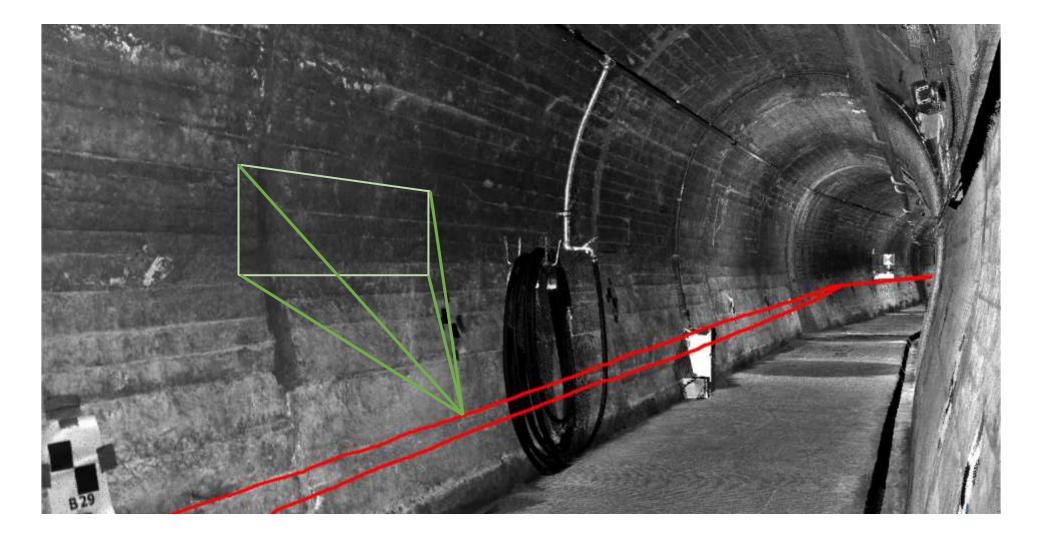
#### BLK2GO









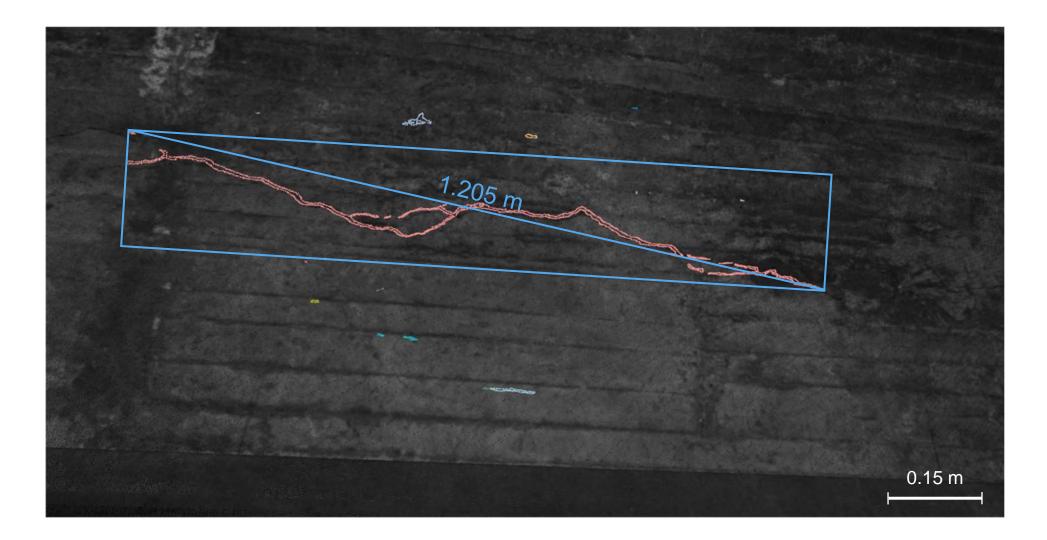










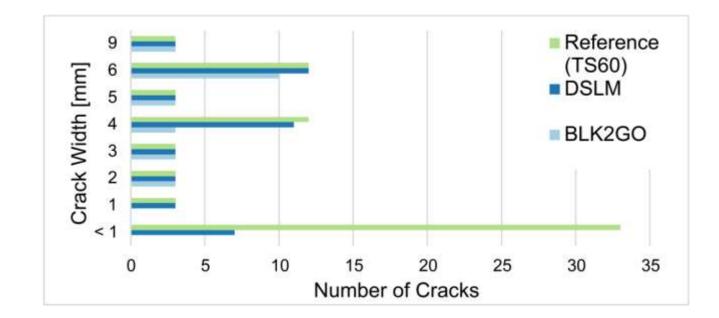




	DSLM	BLK2GO	Depth Camera
Image Localization	needs photogrammetric model, trajectory	trajectory with drift	needs photogrammetric model, trajectory
False-Negative (crack not detected)	~ 30 %	~ 60 %	-
Minimal Detectable Crack Width	> 1 mm	> 2 mm	> 6 mm (no thinner cracks on analyzed pictures)

## Conclusion

- Detecting cracks on DSLM images larger than 1 mm is possible with a prediction accuracy of around 70 %
- DSLM is still most suitable for this application regarding prediction accuracy
- Future system configuration with UAV, 360° camera and fixed light





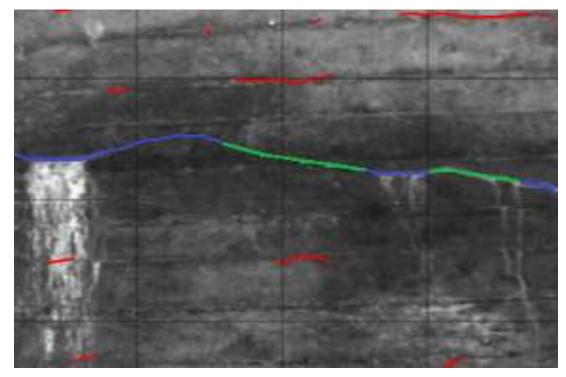
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## Results Depth Camera



*Figure 9: Cracks on the intensity image of the depth camera (green: correct detected, blue: false-negative values, red: false-positive values)* 

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